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## Hyper-class Augmented and Regularized Deep Learning for Fine-grained Image Classification

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Fine-grained image classification (FGIC) is challenging because (i) finegrained labeled data is much more expensive to acquire (usually requiring domain expertise); (ii) there exists large intra-class and small interclass variance. In this paper, we propose a systematic framework of learning a deep CNN that addresses the challenges from two new perspectives: (i) identifying easily annotated hyper-classes inherent in the fine-grained data and acquiring a large number of hyper-class-labeled images from readily available external sources, and formulating the problem into multi-task learning, to address the data scarcity issue. We use two common types of hyper-classes to augment our data, with one being the super-type hyperclasses that subsume a set of fine-grained classes, and another being named factor-type hyper-classes (e.g., different view-points of a car) that explain the large intra-class variance. (ii) a novel learning model by exploiting a regularization between the fine-grained recognition model and the hyper-class recognition model to mitigate the issue of large intra-class variance and improve the generalization performance. The proposed approach also closely relates to attribute-based learning, since one can consider that factor-type hyper-classes are (or can be generalized to) object attributes. We demonstrate the success of the proposed framework on two small-scale fine-grained datasets (Stanford Dogs and Stanford Cars) and on a large-scale car dataset that we collected.



Figure 1: Two types of relationships between hyper-classes and fine-grained classes.

hyper-class regularized learning. As a factor-type hyper-class can be considered as a hidden variable for generating the fine-grained class, therefore we model  $Pr(y|\mathbf{x})$  by

$$\Pr(y|\mathbf{x}) = \sum_{\nu=1}^{K} \Pr(y|\nu, \mathbf{x}) \Pr(\nu|\mathbf{x})$$
(1)

where  $Pr(v|\mathbf{x})$  is the probability of any factor-type hyper-class v and  $Pr(y|v, \mathbf{x})$  specifies the probability of any fine-grained class given the factor-type hyperclass and the input image  $\mathbf{x}$ . If we let  $\mathbf{h}(\mathbf{x})$  denote the high level features of  $\mathbf{x}$ , we model the probability  $Pr(v|\mathbf{x})$  by a softmax function

$$\Pr(\nu|\mathbf{x}) = (\exp(\mathbf{u}_{\nu}^{\top}\mathbf{h}(\mathbf{x}))) / (\sum_{\nu'=1}^{K} \exp(\mathbf{u}_{\nu'}^{\top}\mathbf{h}(\mathbf{x})))$$
(2)

where  $\{\mathbf{u}_{v}\}$  denote the weights for the hyper-class classification model. Given the factor-type hyper-class *v* and the high level features **h** of **x**, the probability  $Pr(y|v, \mathbf{x})$  is computed by

$$\Pr(y = c | v, \mathbf{x}) = (\exp(\mathbf{w}_{v,c}^{\top} \mathbf{h}(\mathbf{x}))) / (\sum_{c=1}^{C} \exp(\mathbf{w}_{v,c}^{\top} \mathbf{h}(\mathbf{x})))$$
(3)

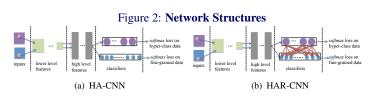
where  $\{\mathbf{w}_{v,c}\}$  denote the weights of factor-specific fine-grained recognition model. Putting together (2) and (3), we have the following predictive probability for a specific fine-grained class, and we use this equation to make the final predictions

$$\Pr(\mathbf{y} = c | \mathbf{x}) = \sum_{\nu=1}^{K} \frac{\exp(\mathbf{w}_{\nu,c}^{\top} \mathbf{h}(\mathbf{x}))}{\sum_{c=1}^{C} \exp(\mathbf{w}_{\nu,c}^{\top} \mathbf{h}(\mathbf{x}))} \frac{\exp(\mathbf{u}_{\nu}^{\top} \mathbf{h}(\mathbf{x}))}{\sum_{\nu'=1}^{K} \exp(\mathbf{u}_{\nu'}^{\top} \mathbf{h}(\mathbf{x}))}$$
(4)

We introduce the following regularization between  $\{\mathbf{w}_{v,c}\}$  and  $\{\mathbf{u}_v\}$ ,

$$R(\{\mathbf{w}_{\nu,c}\},\{\mathbf{u}_{\nu}\}) = \frac{\beta}{2} \sum_{\nu=1}^{K} \sum_{c=1}^{C} \|\mathbf{w}_{\nu,c} - \mathbf{u}_{\nu}\|_{2}^{2}$$
(5)

The regularization is responsible for *transferring the knowledge* to the perviewpoint category classifier and thus helps mode the intra-class variance in



the fine-grained task. The only difference for super-type hyper-class regularized deep learning is on  $Pr(y|v, \mathbf{x})$ , which can be simply modeled by

$$\Pr(y = c | v_c, \mathbf{x}) = (\exp(\mathbf{w}_{v_c, c}^\top \mathbf{h}(\mathbf{x}))) / (\sum_{c=1}^{C} \exp(\mathbf{w}_{v_c, c}^\top \mathbf{h}(\mathbf{x})))$$

since the super-type hyper-class  $v_c$  is implicitly indicated by the fine-grained label *c*. The regularization then becomes

$$R(\{\mathbf{w}_{v_c,c}\}, \{\mathbf{u}_{v}\}) = \frac{\beta}{2} \sum_{c=1}^{C} \|\mathbf{w}_{v_c,c} - \mathbf{u}_{v_c}\|_2^2$$
(6)

Table 3: Accuracy on Large-

scale Cars dataset

**Experimental Results** 

Table 1: Accuracy on Stanford-Cars [2] dataset.

Accuracy(%)
69.5
73.9
54.1
68.6
69.8
83.1
76.7
80.8
83.5
86.3

Tab	le	2:	Accuracy	on	Stanfor	d-
Dog	rs	dat	aset			

=

Dogs dataset.		scale Cars ualaset.	
Method	Acc	Method	Acc
UGA	57.0	ImageNet-Feat-LR	42.8
Gnostic Fields	47.7	CNN	81.6
CNN	42.3		
HA-CNN (ours)	48.3	HA-CNN (ours)	82.4
HAR-CNN (ours)	49.4	HAR-CNN (ours)	83.6

Our network structure and experiment settings are built upon Alex-Net [3]. experimental results demonstrate that, when training on small-scale dataset from scratch and without any fine-tuning, the proposed approach enables us to train a model that yields reasonably good performance. When integrated in the ImageNet fine-tuning process [1], our approach significantly outperforms the current state-of-the-art on Stanford Cars dataset. To further explore if the proposed framework is still useful when training on large-scale FGIC, we collect a large dataset and perform experiments similar to those for the Stanford Cars data.

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This is an extended abstract. The full paper is available at the Computer Vision Foundation webpage.