

# Mapping Visual Features to Semantic Profiles for Retrieval in Medical Imaging

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#### **Abstract**

Content based image retrieval is highly relevant in medical imaging, since it makes vast amounts of imaging data accessible for comparison during diagnosis. Finding image similarity measures that reflect diagnostically relevant relationships is challenging, since the overall appearance variability is high compared to often subtle signatures of diseases. To learn models that capture the relationship between semantic clinical information and image elements at scale, we have to rely on data generated during clinical routine (images and radiology reports), since expert annotation is prohibitively costly. Here we show that re-mapping visual features extracted from medical imaging data based on weak labels that can be found in corresponding radiology reports creates descriptions of local image content capturing clinically relevant information. We show that these semantic profiles enable higher recall and precision during retrieval compared to visual features, and that we can even map semantic terms describing clinical findings from radiology reports to localized image volume areas.

### 1. Introduction

Radiologists have to identify subtle local patterns or *findings* in medical imaging data relevant for diagnosis or the evaluation of treatment outcome. Retrieving and comparing similar cases is critical during this process. However, the variability of visual appearance in these data is high compared to often subtle features that are informative regarding disease differentiation. This causes content based image retrieval quality to suffer. At the same time, approaches that rely on large numbers of annotated ground truth examples are infeasible in the clinical context due to high costs of expert annotation. Instead, methods have to be able to learn information that is generated during clinical routine: images, and radiology reports.

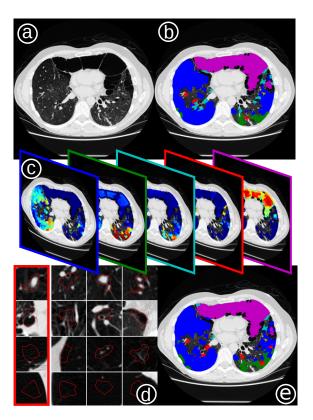


Figure 1: In medical imaging (a) only a small part of the information captured by visual features relates to relevant clinical information such as diseased tissue types (b). However, this information is typically only available as sets of reported observations on the image level. Here, we demonstrate how to link visual features to semantic labels (c), in order to improve retrieval (d) and map these labels back to image regions (e).

In this paper we propose a method that re-maps purely visual features to features that link appearance to weak semantic information that may be extracted from radiology reports describing diagnostically relevant findings in the im-

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ages. The resulting *semantic profiles* capture visual information linked to diagnostic findings. Results demonstrate that this not only improves retrieval accuracy, but allows to map semantic terms from radiology reports to localized image content. The extraction and identification of relevant terms in radiology reports is not in the scope of this paper.

Content based image retrieval (CBIR) techniques are particularly relevant for medical imaging data since, during search, only imaging data is available, while the goal of the search is to find candidates for textual descriptions of the imaging findings. Visual retrieval approaches are hampered by the lack of a one-to-one mapping between visual appearance, its interpretation, and the determination of corresponding findings. This is sometimes referred to as the semantic gap [24]. It has been addressed by carefully selecting specific features that show good retrieval results during experiments [5]. This does not scale well to arbitrary diseases, and is limited by the a priori chosen feature extractors. Adapting feature extractors can overcome part of this limitation, by learning so-called bags of visual words from un-annotated trianing imaging data [4]. While this improves the representative power of the descriptors for the variability occurring in a specific data-set, features are dominated by the overall variability, and not necessarily by characteristics linked to diseases.

An alternative is classification that learns a mapping between local image descriptors and corresponding annotations (e.g., a voxel-wise labeling of the pathological tissue). Typically, the annotation of data sets sufficiently large to allow supervised training of accurate classifiers that differentiate often subtle features is infeasible, since expert annotations are too costly. Instead we have to learn from available clinical data, typically consisting of images and corresponding radiology reports, that hold an expert description of the image content. Once these reports are mapped to a terminology such as RadLex<sup>1</sup> [15], one can pose the problem as a weakly-supervised learning task, or multi-label multi-instance learning (MIL).

A variety of MIL techniques are reported in the literature. MIL primarily aims to solve the problem of classifying bags by predicting which set of classes they contain (e.g. for image categorization [22, 26]). Many techniques are adaptations of supervised approaches such as MIForest [16] or SVM for MIL [1], or distance metric learning algorithms for MIL [13, 9]. Shotton *et al.* proposed randomized decision trees on pixel color and intensity values as features to generate a visual vocabulary that is sensitive to semantic labels [23]. While designed for labelled training data, he showed that in a weakly supervised setting, the class distributions in the leafs still convey discriminative power. Berg *et al.* performed automatic attribute discovery from noisy

web data by linking images and image regions to terms occurring in associated text using a MIL framework [2]. The latter learn a distance metric with the objective to decrease the distance between bags that share labels and increase the distance between bags that do not share any labels.

Retrieval related to clinical findings such as lung texture poses a very particular form of MIL different to standard MIL metric learning techniques in several aspects. The number of instances in the bags is substantially higher compared to standard MIL data reported in literature ( $\gg 1000$  vs.  $\sim 10$  as in e.g. [13, 9]) or MI benchmark datasets such as Fox, Tiger, Elephant. The optimization problem in [9] grows quadratically with the number of instances. Furthermore, when analysing medical imaging data, the bags are heavily skewed, each bag containing a large portion of healthy instances since even patient lungs contain healthy tissue. This poses challenges to distance definitions on the bag level where the minimum distance among the instances of two bags is used to judge their relationship [13, 9].

Classifying the query and performing the retrieval on the basis of a class specific feature vector was discussed in [8], but is limited by the need for annotation, classifier accuracy, and the assumption that all information is encoded in the trained class labels. Retrieving anomalies based on classification neglects intraclass variability, and differences of characteristics that go beyond a limited set predefined classes due to various factors such as the age of the patient, smoking history, and extend of the disease [7].

Instead of training a classifier, we propose to inject semantic terms into the feature learning process, to augment the representation of relevant characteristics. We use these features to perform content based image retrieval, and to map the terms back to image regions, in order to mark the locations with the strongest link to specific findings. Terms describing the findings are used as sets of weak labels corresponding to an image volume (Figure 2 ). Rather than training a classifier to label image volumes (as in standard MIL approaches) we only re-map the feature vectors to allow sub-sequent algorithms such as indexing and retrieval to focus on image information linked to semantic content of images. The approach relies only on data available in clinical routine and does not require additional annotation. It uses semantic information present in radiology reports as a basis for learning their link to image content. In the experimental evaluation, we demonstrate that the resulting features (semantic profiles) of local image patches improve the precision and recall of disease relevant tissue types by content based image retrieval considerably. Furthermore, we illustrate that the resulting features allow for a mapping of semantic labels to local regions in images. This is important for further learning from combined imaging and textual data, and allows to show users the localized basis of the

<sup>&</sup>lt;sup>1</sup>RadLex is a unified terminology of radiology terms and their relationships. http://www.radlex.org/

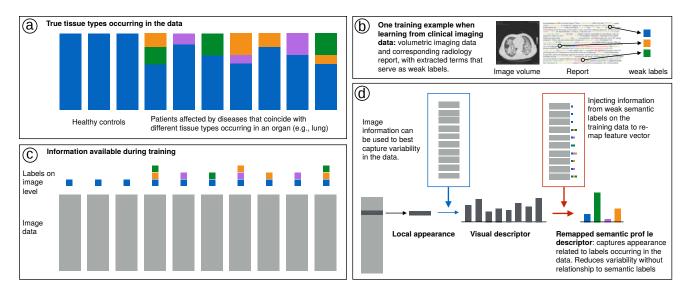


Figure 2: Scheme of learning semantic profiles from a set of image - radiology report pairs. (a) True hidden labeling of the data representing diseases in an organ that coincide with distinct tissue types, blue is healthy tissue. (b) Radiology reports can be used as souce to extract the weak labels. (c) This results in weak labels on the image level are available during training. (d) First, visual appearance is captured by local image descriptors. Then, weak label information is used to remap the local purely visual descriptors to local semantic profiles.

retrieval result.

The learning technique is based on randomized subspace partitioning and subsequent analysis of label distributions in the partitions. The feature space partitioning is performed by so called random ferns [19]. An ensemble of such random ferns is used to embody a model of the label distribution in the feature space. During retrieval, this distorts the similarity function so that it is dominated by partitions that are informative for the difference between specific pathologies / classes. The iterative randomized partitioning of a feature space by Random Ferns that we utilize has been used for a fast keypoint recognition technique [18, 19] and as an alternative to k-means clustering for the bag of visual words approach [20, 17], since it offers very fast runtimes.

### 2. Method

The method consists of a training and an indexing- or application phase. During training (Sec. 2.2) multiple dense, random, independent partitionings of the feature space are generated by a random ferns ensemble [19] (Figure 3 (1)). Based on the label distributions in the resulting partitions, a remapping of feature vectors is generated that captures the link between appearance and weak labels (Figure 3 (2)). In the indexing- or application phase (Sec. 2.3), an ensemble affinity for a novel record to each class is calculated, and a corresponding semantic profile feature vector is generated.

### 2.1. Problem definition

We are given a set  $\mathcal{I} = \{\mathbf{I}_1, \mathbf{I}_2, ..., \mathbf{I}_I\}$  of I images. For each image, there exists an oversegmentation of  $S_i$  supervoxel [12] where  $p_{i,s}$  identifies the supervoxel s in image  $\mathbf{I}_i$ . We collect all  $N = (\sum_{i=1}^I S_i)$  super voxel identifiers  $\mathcal{N} = \{p_{1,1}, \ldots, p_{1,S_1}, p_{2,1}, \ldots, p_{I,1}, \ldots, p_{I,S_I}\}$  in all I images. We assume that each supervoxel belongs to one of T tissue classes (e.g. 'healthy','groundglass', ...), defining a labeling

$$l: \mathcal{N} \to \{1, \dots, T\}.$$
 (1)

During training this labeling is not given for individual supervoxels. Instead, for each image, we are given a set of labels  $\mathcal{T}_i \subseteq \{1,\ldots,T\}$  corresponding to an entire image volume. Similar to *multi label multi instance learning*, for each of these labels, there exists at least one supervoxel in the volume. This results in training data

$$\langle \mathbf{I}_i, \mathcal{T}_i \rangle_{i=1,\dots,I},$$
 (2)

i.e., for each image we have a set of supervoxels and a set of labels,  $\langle \mathcal{P}_i, \mathcal{T}_i \rangle$ , where

$$\forall t \in \mathcal{T}_i : \exists p_{i,s} : l(p_{i,s}) = t. \tag{3}$$

To facilitate reading, we define the set  $C_t$  of supervoxels across the entire training set associated with a weak label t by this labeling, so that

$$\forall p_{i,s} : (p_{i,s} \in \mathcal{C}_t) | t \in \mathcal{T}_i. \tag{4}$$

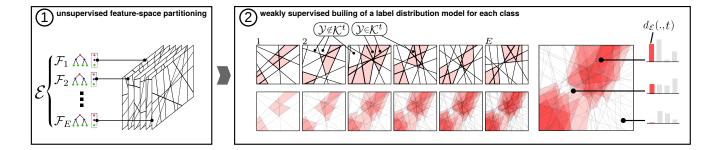


Figure 3: Label distribution model: (1) Multiple random partitionings of the feature space are generated without supervision. (2) For a certain class, the relative term frequency is calculated. To calculate the ensembles affinity prediction of a novel supervoxel to a class, the K partitions with the highest relative term frequencies are used to indicate a ferns vote.

Note that  $\mathcal{C}_t$  contains many supervoxels that do not carry the true label t. We aim for a similarity measure d that is based on the visual appearance of supervoxels, and at the same time reflects the true labels (that are never directly accessible during training) of two supervoxels. Let  $a,b,c\in\mathcal{N}$  be three supervoxel identifiers. We want to optimize d to come as close to the desired property of:

$$d(a,b) < d(a,c) \mid l(a) = l(b) \land l(a) \neq l(c)$$
 (5)

To this end, we generate a visual descriptor  $\mathbf{f}_{p_{i,s}}^{SP}$  for each supervoxel, so that the euclidean distance between the descriptors comes close to this aim.

## 2.2. Linking weak labels and features

We are given arbitrary texture descriptors f describing the visual contents of the supervoxels. We learn models of the class label distributions in this primary feature space, and remap each texture descriptors to a new descriptor that is sensitive to the anomaly classes in the weakly labeld training data.

**Random Subspace Partitioning:** We use Random Ferns [18, 19] for space partitioning. A fern  $\mathcal{F}$  is a sequence of binary decision functions

$$\mathcal{F} = \langle \mathcal{L}_1, \mathcal{L}_2, \dots, \mathcal{L}_L \rangle, \tag{6}$$

which when applied to a feature vector **f** result in a binary vector encoding the partitioning of the feature space

$$\mathcal{L}(\mathbf{f}) : \mathbf{f} \mapsto \{0, 1\}, \text{ and } \mathcal{F}(\mathbf{f}) : \mathbf{f} \mapsto \{0, 1\}^L.$$
 (7)

The binary codes represent values in the range  $(1, ..., 2^L)$ . We use the binary decision function suggested by Pauly *et al.* [20]:

$$\mathcal{L}_{l}(\mathbf{f}) = \begin{cases} 0 & \text{if } (\mathbf{s}_{l}^{sub_{l}})^{\top} \cdot \mathbf{f}^{sub_{l}} \leq \tau_{l} \\ 1 & \text{if } (\mathbf{s}_{l}^{sub_{l}})^{\top} \cdot \mathbf{f}^{sub_{l}} > \tau_{l} \end{cases}$$
(8)

For a split test, a set of dimensions from the feature space is randomly selected and only the corresponding sub vector  $\mathbf{f}^{sub_l}$  is considered. The sub vectors are then projected into a one-dimensional space by building the dot product with unit vector  $\mathbf{s}_l^{sub_l}$  randomly sampled from the unit sphere so that  $(\mathbf{s}_l^{sub_l})^{\top} \cdot \mathbf{f}^{sub_l}$  is a scalar. To get a binary value, this scalar is compared to a threshold  $\tau_l$ . We randomly sample this threshold from the projected values. We generate an ensemble  $\mathcal E$  of E Random Ferns of depth L to iteratively partition the feature space.

$$\mathcal{E} = \langle \mathcal{F}_1, \dots, \mathcal{F}_E \rangle \tag{9}$$

The ensemble generates  ${\cal E}$  independent partitionings so that

$$\mathcal{E}: \mathbb{R}^d \to \{1, \dots, 2^L\}^E \tag{10}$$

$$\mathcal{E}(\mathbf{f}): \mathbf{f} \mapsto \langle y_1, \dots, y_E \rangle, y \in \{1, \dots, 2^L\}$$
 (11)

We define  $\mathcal{Y}_y^e$  as the set of supervoxels in a certain partition y of fern  $\mathcal{F}_e$  so that

$$\forall i \in \mathcal{N} : i \in \mathcal{Y}_{u}^{e} \mid \mathcal{F}_{e}(\mathbf{f}_{i}) = y \tag{12}$$

**Label Distribution Model:** For all  $\mathcal{Y}_y^e$ , we analyse the ratios of the weak labels according to their relative class frequencies. The relative class frequency makes leaf nodes or partitions comparable with respect to the number of examples of a certain class they hold. Some leaf nodes may hold very few or even just a single example. We use Laplace smoothing [3, 21] to diminish an overrating of such small example groups. We define  $f(\mathcal{Y}_y^e, t)$  as the smoothed relative class frequency of t in the leaf set  $\mathcal{Y}_v^e$ :

$$f(\mathcal{Y}_{y}^{e}, t) = \frac{1 + l(\mathcal{Y}_{y}^{e}, t)}{\gamma + \sum_{j=1}^{T} l(\mathcal{Y}_{y}^{e}, t_{j})}$$
(13)

where  $\gamma$  is a factor to control the impact of the smoothing and  $l(\mathcal{Y}_y^e, t)$  gives the number of examples in the leaf node  $\mathcal{Y}_y^e$  that are represented in  $\mathcal{C}_t$ :

$$l(\mathcal{Y}_y^e, t) = \sum_{i=1}^N \mathbf{1}_{\mathcal{Y}_y^e}(i) \mathbf{1}_{\mathcal{C}_t}(i)$$
 (14)

The use of f reduces the value of the relative class frequency for small partitions.

## 2.3. Mapping the features to the classes

We define

$$\mathcal{K}^t = \{ \langle e_1, y_1 \rangle, \dots, \langle e_K, y_K \rangle \}$$
 (15)

as the set of the K leaf nodes in the ensemble with the K highest values of f(.,t) indexed by fern index  $e_i$  and leaf index  $y_i$ . Let's consider a hypothetical supervoxel that is represented in all leaf nodes in  $\mathcal{K}^t$ . This supervoxel is seen as a prototype representative of class t. Note, that this represents an area rather than a point in the feature space. We interpret the similarity of a supervoxel to this prototype as a measure of its affinity to the class. We construct an affinity indicator for a supervoxel j reflecting its affinity to a class t:

$$d_{\mathcal{E}}(j,t) = \sum_{e=1}^{E} \sum_{y=1}^{2^{L}} \mathbf{1}_{\mathcal{Y}_{y}^{e}}(j) \mathbf{1}_{\mathcal{K}^{t}}(\langle e, y \rangle)).$$
 (16)

 $d_{\mathcal{E}}(j,t)$  sums the occurrences of a supervoxel in  $\mathcal{K}^t$  so that  $d_{\mathcal{E}}(j,t) \in 0,\ldots,E$ .

For a supervoxel  $j, d_{\mathcal{E}}(j,t)$  is calculated for  $t=1,\ldots,T$  resulting in a new vector. The maximum possible number of votes from the ensemble for one class is E. In practice, this value will be smaller and vary between different classes. Thus, we scale each dimension to [0,1] resulting in the new feature vector for each supervoxel that we call semantic profile (SP):

$$\mathbf{f}_j^{SP} \in [0, 1]^T = [d_{\mathcal{E}}(j, 1), \dots, d_{\mathcal{E}}(j, T)]]$$
 (17)

We expect that this descriptor provides a higher specificity in retrieving representatives of the learned anomaly classes compared to a feature vector resulting from a descriptor that is learned on visual information only.

## 3. Evaluation

We evaluated two aspects of semantic profiles: (1) do they improve retrieval accuracy in clinical imaging data, and (2) do they map terms in radiology reports accurately to regions in the corresponding imaging data? We want to understand if injecting weak label information can improve retrieval over purely visual features, and if the corresponding descriptors indicate a mapping of terms to the individual volumes.

**Data** We performed experiments on a set of 300 high resolution computed tomography (HRCT) scans of lungs provided by LTRC [11]. All voxels in the images are labelled into one of five tissue classes: healthy lung texture and four tissue types (ground-glass, reticular pattern, honey combing, emphysema) occuring in interstitial lung diseases (ILD). Only voxels within the lungs are analyzed. We transform all volumes to an isotropoic voxel resolution of  $0.7mm^3$  in advance, and perform over-segmentation of the volumes to monoSLIC supervoxels of an average size of  $1cm^3$  [12]. We consider only supervoxels consisting of at least 70% of one label, to avoid partial volume effects.

For the experimental validation we created a weakly labeled data set from the labeled lung data. To simulate a varied distribution of labels in the training dataset we sample 683201 supervoxels of which 460912 show healthy, 42183 show ground-glass, 7461 show reticular, 12436 show honeycombing and 160980 show emphysema. The sets  $C_t$  are bagged to create a set equivalent to what would be training data from a clinical source for the proposed algorithm. Only the set membership  $C_1..C_5$  is known to the learning algorithm. Since their distribution is relevant we show it in Table 1. The negative instances in each bag are chosen to represent in extent 10% of the population of the other classes. Healthy lung texture is a special case as it can be expected to be present in every lung. In a real world setting, additional control examples of healthy lung texture can be sampled from records of healthy lungs. Thus, a set of healthy representatives  $C_1$  can be obtained.

All experiments are performed by 10-fold cross-validation. The splitting into training and testset is performed under consideration of the original volume membership of the supervoxels into 30 test and 270 training volumes in order to prevent any wihtin-patient overlap between training and test set.

We extract two texture descriptors for each supervoxel. (1) 1200-dimensional Texture Bags [4], a multi-scale Bag of Visual Words (BVW) approach on Local Binary Patterns (in the following abbreviated with BVW), and (2) 52-dimensional Haralick features [10] on  $21 \times 21 \times 21$  patches around the center of the supervoxel. Both methods have been used for retrieval of anomalies in lung CTs [4, 14, 25, 6]. For each descriptor, we generate a semantic profile mapping. We term the novel features SP-BVW and SP-Haralick for the respective embedding into the 5-dimensional (5 indicators for healthy and the 4 anomalies) feature space. For all experiments we fixed the parameters for number of ferns E=1000 and fern depth L=8.

**Retrieval** To evaluate retrieval we randomly choose 200 supervoxels of each anomaly class from the testset as queries (overall 1000 queries). Based on each query, we rank the training data using Euclidean distance among 4 feature vectors: (1) BVW, (2) Haralick, (3) SP-BVW, and (4) SP-

Anomaly name	Class t=	# Healthy	# Ground-glass	# Reticular	# Honeycombing	# Emphysema	Σ	TP in %
Healthy	1	276547	0	0	0	0	276547	100
Ground-glass	2	46091	41682	746	1246	16098	105563	40
Reticular	3	46091	4138	7464	1246	16098	75037	10
Honeycombing	4	46091	4138	746	12463	16098	79536	13
Emphysema	5	46091	4138	746	1246	160980	213201	76

Table 1: Composition of the sets  $C_1$  to  $C_5$ . Each line shows the distribution of the true classes in one set. The sum of supervoxels  $\Sigma$  in each set and the share of True Positive representatives (TP) are shown on the right. During learning, only the set ( $C_1$  to  $C_5$ ) memberships but not the true classes are visible to the training algorithm.

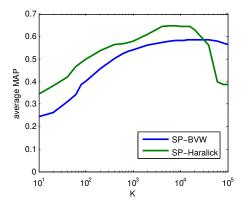


Figure 4: Effect of parameter K on the retrieval performance. The plot shows the averaged MAP over the five classes for values of K from 10 to  $10^5$ .

Haralick. We compare recall and precision achieved by these descriptors.

Mapping terms to images We map the individual coefficients of the semantic profiles back to the volume to evaluate if they allow for localization of the tissue areas responsible for specific retrieval. We evaluate this qualitatively (Figure 6) and quantitatively (Table 3), by classifying supervoxels based on the highest coefficient of the corresponding semantic profile. Note that this is not a sophisticated classifier, but an inspection if the features capture the actual tissue properties accurately. These experiments are performed on volumes of the test set.

#### 4. Results

**Retrieval** Figure 5 shows precision-recall curves for the five tissue classes. Baseline, i.e., random-ranking is indicated by a gray line. Table 2 lists the corresponding mean average precision values (MAP). Semantic profiles return better precision for all anomaly classes in comparison to the corresponding purely visual descriptors. A distinctive improvement can be seen from BVW to SP-BVW for the retrieval of ground-glass supervoxels (MAP of 0.22 to 0.71). Comparing the visual descriptors to the semantic profile embedding

the averaged MAP over the five classes is raised from 0.38 to 0.58 for BVW and from 0.53 to 0.65 for Haralick. Figure 4 shows the effect of the parameter K on the retrieval performance. If K is chosen too low, the model of the label distribution in the feature space is too sparse, if K is chosen too high the model associates regions in the feature space that have no association to the modelled class. Figure 7 shows examples of queries and resulting nearest neighbor supervoxels using BVW and SP-BVW descriptors. One can see the suppression of the (for this anomaly irrelevant) rotation variant features of the BVW descriptor resulting from re-mapping to semantic profiles.

Mapping terms to images Figure 6 shows ground truth labelings of volume data, and a labeling obtained by assuming that the highest semantic profile coefficient is a good estimator for the correct label. Corresponding quantitative results for the best performing descriptor (SP-Haralick) are shown in Table 3. The right side of Figure 6 shows the mapping of the semantic profiles back to the imaging data. Note how the distribution of voxel scores learned from weakly labeled volumes, mirrors the true voxel labels very well.

Runtime To generate E=1000 partitionings, runtime for the unsupervised part of the training (Figure 3 (1)) on 615000 52-dimensional Haralick features is 85 seconds. The iterative modeling of the label distribution in the feature space (Figure 3 (2)) needs 20 seconds per class (100 seconds for 5 classes). This runtime experiments have been performed on a 12-core 24 thread Intel Xeon processor utilizing a Matlab implementation of the method. The calculation of the semantic profiles for 7526 haralick descriptors (average number of supervoxels for a volume) needs 1.37 seconds.

## 5. Conclusion

In this paper we propose and evaluate *semantic profiles* that capture visual information related to clinically relevant terms. Training of semantic profiles is weakly supervised. It is based on pairs of image volumes and corresponding sets of terms in radiology reports that describe radiological findings present in the imaging data. We show that the resulting descriptor substantially improves retrieval precision and re-

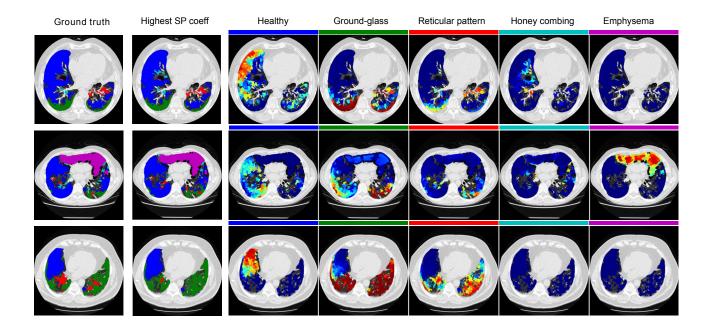


Figure 6: Left: Mapping terms to the volume data. Ground truth labeling not available during training and the label of highest semantic profile coefficient for the same image slice. Right: maps of the semantic profiles used for retrieval mapped back to the data. Red indicates high values for a pathology pattern, blue indicates low values.

	Healthy	Gound-glass	Reticular	Honeycombing	Emphysema	
BVW	86	22	14	5	61	
SP-BVW	93	71	32	18	76	
Haralick	92	77	12	20	64	
SP-Haralick	93	83	20	42	86	

Table 2: MAP in % for retrieval of four anomaly classes and healthy. Semantic Profile embedding increases the MAP significantly over the visual descriptors used as input for the learning algorithm. Best MAP for each class is marked bold.

call. Furthermore it allows to map terms back to regions in the imaging data. The method improves retrieval in medical imaging data since it augments the representation of image characteristics that are linked to diagnostically relevant terms. Importantly, it can be trained based on data generated during clinical routine, without the need for additional annotation.

	Healthy	Gound-glass	Reticular	Honeycombing	Emphysema
Healthy	114922	459	35	353	34
Gound-glass	227	3789	116	2	0
Reticular	80	266	381	16	0
Honeycombing	471	20	22	717	2
Emphysema	2247	0	1	36	13811
Sensitivity	0.99	0.92	0.51	0.57	0.86
Specificity	0.86	0.99	1.00	1.00	1.00

Table 3: Confusion Matrix and Sensitivity and Specificity values for supervoxel labeling on the basis of the highest semantic profile coefficient on SP-Haralick

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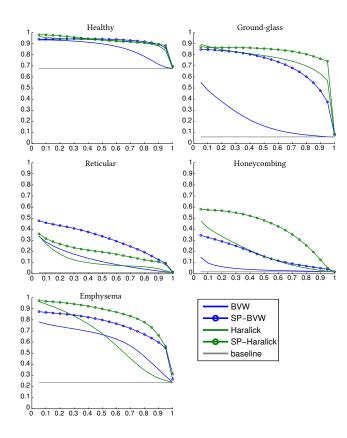
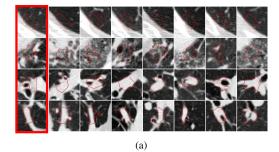


Figure 5: Precision Recall curves for the four anomaly classes and healthy. Comparison of the texture descriptors BVW and Haralick and the Semantic Profile embeddings of both.

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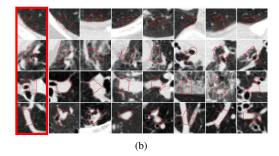


Figure 7: Nearest neighbors for four different query supervoxels (red box) using (a) BVW descriptor and (b) the Semantic Profiles trained on BVW.

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